

TA16

series



Product Segments

- Care Motion
- Comfort Motion

TiMOTION's TA16 series linear actuator is similar to the TA2 linear actuator, but is specifically designed for low-noise medical applications where a compact linear actuator is needed. It is available with optional IP66 protection and Hall sensors for position feedback. Certificates for the TA16 include IEC60601-1 and ES60601-1.

General Features

Voltage of motor 12V DC or 24V DC Maximum load 3,500N in push Maximum load 2,500N in pull

Maximum speed at full load 13.5mm/s (with 1,500N in a push or pull

condition)

Standard stroke 20~1000mm Minimum installation dimension Stroke+112mm

Color Silver
Protection class Up to IP66
Option Hall sensor(s)

Certificate EN60601-1 and IEC60601-1 compliant

Operational temperature range $+5^{\circ}\text{C} \sim +45^{\circ}\text{C}$ With very low noise, small size for easy installation

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Load and Speed

CODE	Load (N)		Self	Typical Curre	Typical Current (A)		Typical Speed (mm/s)	
	Push	Pull	Locking Force (N)	No Load 32V DC	With Load 24V DC	No Load 32V DC	With Load 24V DC	
Motor S	peed (3800RP	M, Duty Cyc	le 10%)					
Α	2500	2500	2500	0.9	2.8	5.2	3.0	
В	2000	2000	2000	0.9	2.8	8.3	4.7	
С	1500	1500	1000	0.9	2.8	11.9	7.0	
D	1000	1000	1000	1.0	2.8	17.7	10.3	
Motor S	peed (5600RP	M, Duty Cyc	le 10%)					
G	3500	2500	2000	1.5	4.7	12.0	6.5	
J	2000	2000	1000	1.5	3.2	17.0	10.5	
K	1500	1500	700	1.5	3.5	23.5	13.5	

Note

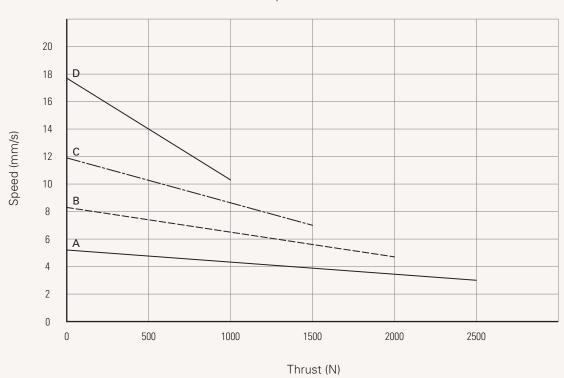
- 1 With a 12V motor, the current is approximately twice the current measured in 24V; speed will be similar for both voltages.
- ${\color{red} 2} \ \, \text{Above self lock performance needs working with TiMOTION control system}.$



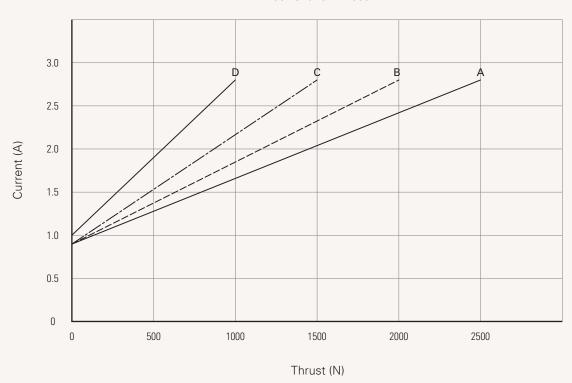
Performance Data (24V DC Motor)

Motor Speed (3800RPM, Duty Cycle 10%)

Speed vs. Thrust



Current vs. Thrust



Note

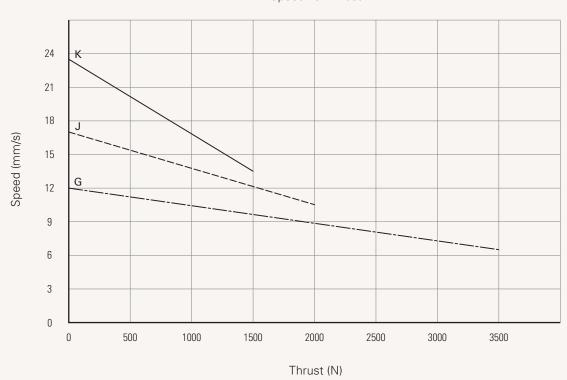
1 The performance data in the curve charts shows theoretical value.



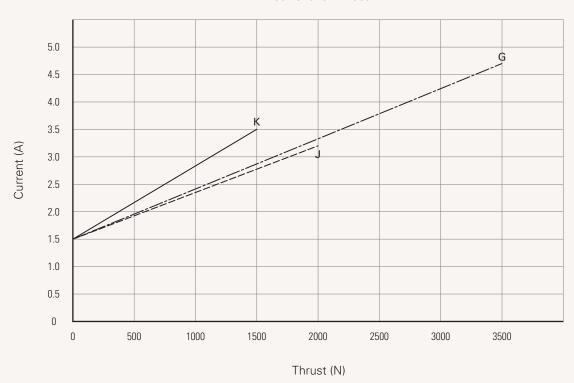
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Current vs. Thrust



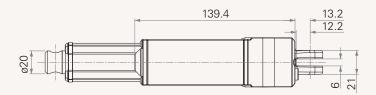
Note

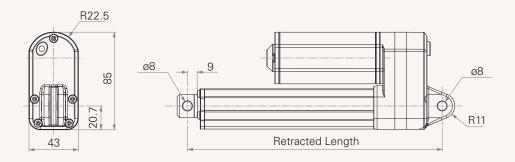
1 The performance data in the curve charts shows theoretical value.



Drawing

Standard Dimensions (mm)





Wire Definitions CODE* Pin 2 3 5 6 (yellow) (green) (red) (white) (black) (blue) 1 extend (VDC+) N/A retract (VDC+) N/A N/A N/A 2 extend (VDC+) middle switch pin B middle switch pin A retract (VDC+) N/A N/A 3 extend (VDC+) upper limit switch N/A retract (VDC+) lower limit switch common 4 extend (VDC+) retract (VDC+) lower limit switch upper limit switch medium limit switch common

Note

* See ordering key - functions for limit switches



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Retracted length (mm)

- 1. Calculate A+B+C+D=Y
- 2. Retracted length needs to \geq Stroke+Y

A. Attachment	Rear Attachment Code
Front Attachment Code	1, 2, 3
1, 2, 3	+112
4, 5, 6	+122

B. Load vs Stroke	Load (N)	Load (N)			
Stroke (mm)	< 3500	= 3500			
20~150	-	+5			
151~200	+8	+13			
201~250	+8	+13			
251~300	+13	+18			
301~350	+13	+18			
351~400	+18	+23			

For stroke over 400mm, +5mm for each incremental 50mm stroke.

C. Special Functions for Spindle Sub-Assembly	Load and Speed Code
Code	А, В
0, 2	-
1, 3	+10

D. Signal Output			
Code			
0, 4, 5	-		
1	+36		



TA16 Ordering Key



Voltogo	1 12\/		2 241/		
Voltage	1 = 12V		2 = 24V		
Load and Speed	See page 2.				
Stroke (mm)	_				
Retracted Length (mm)	See page 6.				
Rear Attachment (mm)	1 = Aluminum casting, U clevis, width 6.0, depth 12.2, hole 6.4, one piece casting with gear box 2 = Aluminum casting, U clevis, width 6.0, depth 12.2, hole 8.0, one piece casting with gear box 3 = Aluminum casting, U clevis, width 6.0, depth 12.2, hole 10.0, one piece casting with gear box				
Front Attachment (mm)	5 = Aluminum casting, U cl	slot, hole 8.0	9.80		
Direction of Rear Attachn	nent (Counterclockwise)	1 = 90°	2 = 0°		
IP Rating	1 = Without	2 = IP54	3 = IP66		
Functions for Limit Switches	1 = Two switches at full retracted/extended positions to cut current 2 = Two switches at full retracted/extended positions to cut current + 3rd LS to send signal 3 = Two switches at full retracted/extended positions to send signal 4 = Two switches at full retracted/extended positions to send signal + 3rd LS to send signal				
Special Functions for Spindle Sub-Assembly	0 = Without	1 = Safety nut	2 = Standard push only	3 = Standard push only + safety nut	
Output Signals	0 = Without	1 = POT	4 = One Hall sensor	5 = Two Hall sensors	
Connector	1 = DIN 6pin, 90° plug 2 = Tinned leads 4 = Big 01pin, plug		E = MOLEX 8pin, plug F = DIN 6pin, 180° plug G = Audio plug		
		system, water proof, anti pull)			